

E-ProTran: Efficient Probabilistic Transformers for Forecasting



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Can we design probabilistic transformers with higher efficiency?

Yes, E-ProTran has improved inference speed and scalability with comparable performance!

Motivation and Contributions

Transformers excel in handling long-range dependencies in sequential data and show promise in time series analysis. However, **their complexity often results in overparameterization, extended training times, and scalability challenges**, especially with complicated generative model assumptions. In this work, we propose Efficient Probabilistic Transformers (E-PROTRAN), a re-design of Probabilistic Transformers (PROTRAN) to mitigate these problems.

Formulation and Problem Setting

Results

We present the performance metrics for ELECTRICITY and WIKIPEDIA. The average predictions are from 100 forward passes; shaded areas show 1 standard deviation.

Model			Electricity					
Туре	Att.	Rec.	$CRPS_sum$	CRPS	RMSE	#Params	Forw. Pass (sec)	
ProTran	LIA	\checkmark	0.030	0.069	439.2	501,924	0.064 ± 0.001	
E-ProTran	LIA	\checkmark	0.024	0.075	501.7	382,084	0.044 ± 0.001	
E-ProTran	LI	\checkmark	_	_	_	_	_	
E-ProTran	L	\checkmark	0.024	0.072	530.2	315,652	$0.002~\pm~0.000$	
E-ProTran	LIA	X	0.030	0.077	582.8	382,084	0.044 ± 0.001	
E-ProTran	LI	×	_	_	_	_	—	
E-ProTran	L	X	0.029	0.079	598.7	315,652	$\textbf{0.003}~\pm~\textbf{0.001}$	

We work with multivariate time series $x_{1:T} \in \mathbb{R}^{T \times d}$, where $x_t \in \mathbb{R}^d$ is a *d*-dimensional data vector at the discrete time step $t \in \mathbb{N}^+$. We parameterize a generative model with joint of $p_{\psi,\theta}(x_{1:T}, z_{1:T}|x_{1:t_0}, c_{1:T})$ can be used for forecasting in temporal settings. The baseline work PROTRAN uses

$$p_{\psi}(z_{1:T}|x_{1:t_0}, c_{1:T}) = \prod_{l=1}^{L} \prod_{t=1}^{T} p_{\psi}(z_t^{(l)}|z_{1:t-1}^{(l)}, z_{1:T}^{(l-1)}, x_{1:t_0}, c_{1:T}) \quad (1)$$

$$p_{\theta}(x_{1:T}|z_{1:T}) = \prod_{t=1}^{T} p_{\theta}(x_t|z_t^{(L)}) \quad (2)$$

where L is number of layers in the encoder, T is length of the temporal data.

E-ProTran

For our model, we have the generative model with components

$$p_{\psi}(z_{1:T}|x_{1:t_0}, c_{1:T}) = \prod_{t=1}^{T} p_{\psi}(z_t|x_{1:t_0}, c_{1:T})$$
(3)
$$p_{\theta}(x_{1:T}|z_{1:T}) = \prod_{t=1}^{T} p_{\theta}(x_t|z_t).$$
(4)

We opt to use



Forecasting on Electricity for the first test sequence. We show 4 of 370 dims.

Model			WIKIPEDIA					
Туре	Att.	Rec.	$CRPS_{sum}$	CRPS	RMSE	#Params	Forw. Pass (sec)	
ProTran	LIA	\checkmark	0.066	0.320	5909.2	1,522,080	0.187 ± 0.003	
E-PROTRAN	LIA	\checkmark	0.075	0.353	6020.0	1,259,584	0.141 ± 0.005	
E-ProTran	LI	\checkmark	0.063	0.328	5932.2	1,126,720	$\boldsymbol{0.007}~\pm~\boldsymbol{0.001}$	
E-ProTran	L	\checkmark	0.063	0.311	5936.8	1,060,416	$\boldsymbol{0.007}~\pm~\boldsymbol{0.002}$	
E-PROTRAN	LIA	X	0.081	0.354	5983.3	1,259,584	0.139 ± 0.005	
E-ProTran	LI	X	0.054	0.327	5945.1	1,126,720	$\textbf{0.007}~\pm~\textbf{0.002}$	
E-ProTran	L	×	0.053	0.316	5906.7	1,060,416	$\boldsymbol{0.007}~\pm~\boldsymbol{0.002}$	



Non-autoregressive attention to reduce computational overhead while allowing information flow over time through layer attention.

Causal attention to lower layers to minimize propagation of error from later time steps, and make sure our predictions are independent of the forecasting length.

Stochastic z_t only at the latent bottleneck; otherwise, it introduces noise in the forward pass and thus affects the gradients during training.

Forecasting on Wikipedia for the first test sequence. We show 4 of 2000 dims.

Looking for More?



* Equal contribution.

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