

E-ProTran: Efficient Probabilistic Transformers for Forecasting

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Can we design probabilistic transformers with higher efficiency?

Yes, E-ProTran has improved inference speed and scalability with comparable performance!

Motivation and Contributions

Transformers excel in handling long-range dependencies in sequential data and show promise in time series analysis. However, their complexity often results in overparameterization, extended training times, and scalability challenges, especially with complicated generative model assumptions. In this work, we propose Efficient Probabilistic Transformers $(E-PROTRAN)$, a re-design of Probabilistic Transformers $(PROTRAN)$ to mitigate these problems.

where L is number of layers in the encoder, T is length of the temporal data.

Formulation and Problem Setting

Stochastic z_t only at the latent bottleneck; otherwise, it introduces noise in the forward pass and thus affects the gradients during training.

 $\sqrt{5}$ 1000 2000 20 40 60 20 60 Time Time

Forecasting on Wikipedia for the first test sequence. We show 4 of 2000 dims.

We present the performance metrics for ELECTRICITY and WIKIPEDIA. The average predictions are from 100 forward passes; shaded areas show 1 standard deviation.

$$
p_{\psi}(z_{1:T}|x_{1:t_0},c_{1:T}) = \prod_{l=1}^{L} \prod_{t=1}^{T} p_{\psi}(\frac{z_t^{(l)}}{z_{1:t-1}^{(l)}}, \frac{z_{1:T}^{(l-1)}}{z_{1:T}}, x_{1:t_0},c_{1:T}) \tag{1}
$$

$$
p_{\theta}(x_{1:T}|z_{1:T}) = \prod_{t=1}^{T} p_{\theta}(x_t|z_t^{(L)}) \tag{2}
$$

E-ProTran

For our model, we have the generative model with components

$$
p_{\psi}(z_{1:T}|x_{1:t_0},c_{1:T}) = \prod_{t=1}^{T} p_{\psi}(z_t|x_{1:t_0},c_{1:T})
$$
(3)

$$
p_{\theta}(x_{1:T}|z_{1:T}) = \prod_{t=1}^{T} p_{\theta}(x_t|z_t).
$$
(4)

We opt to use

Forecasting on Electricity for the first test sequence. We show 4 of 370 dims.

Non-autoregressive attention to reduce computational overhead while allowing information flow over time through layer attention.

Causal attention to lower layers to minimize propagation of error from later time steps, and make sure our predictions are independent of the forecasting length.

Results

We work with multivariate time series $x_{1:T}$ \in $\mathbb{R}^{T \times d}$, where $x_t \in \mathbb{R}^d$ is a d -dimensional data vector at the discrete time step $t \in \mathbb{N}^+$. We parameterize a generative model with joint of $p_{\psi,\theta}(x_{1:T},z_{1:T}|x_{1:t_0},c_{1:T})$ can be used for forecasting in temporal settings. The baseline work ProTRAN uses

Looking for More?

[∗] Equal contribution.

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